

The effect of noise on the number of extreme points

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Introduction

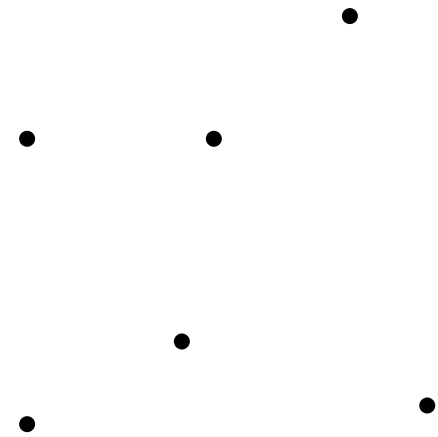
Geometric data structure

Complexity analysis

Limits: structure and precision

Geometric data structures

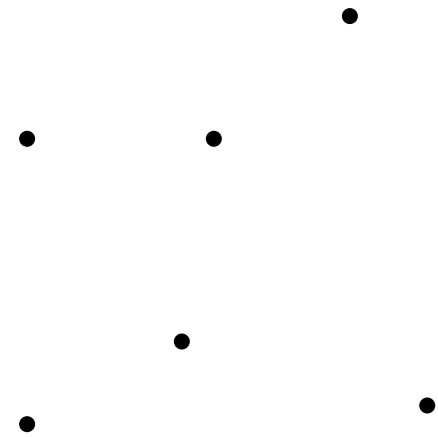
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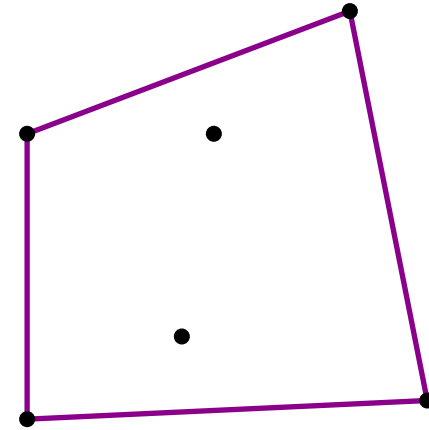


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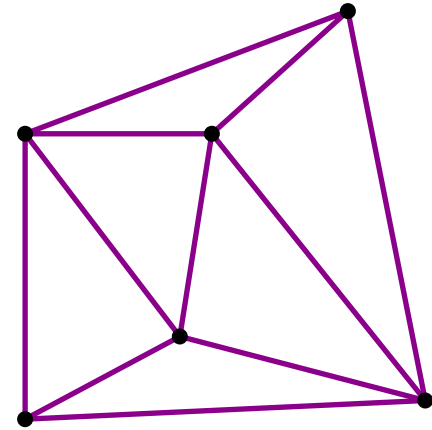


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- ★ the *Delaunay triangulation* of P

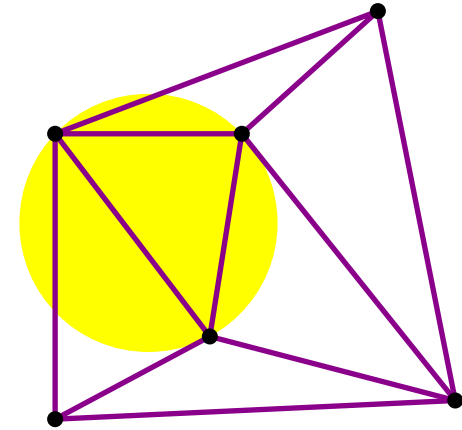


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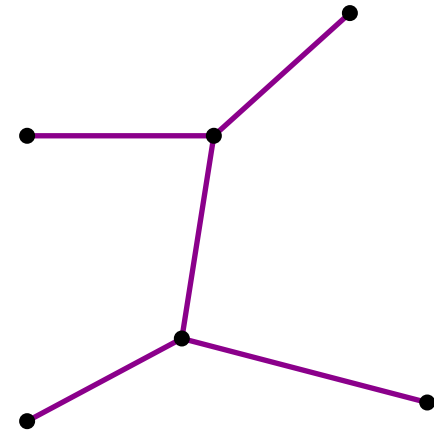


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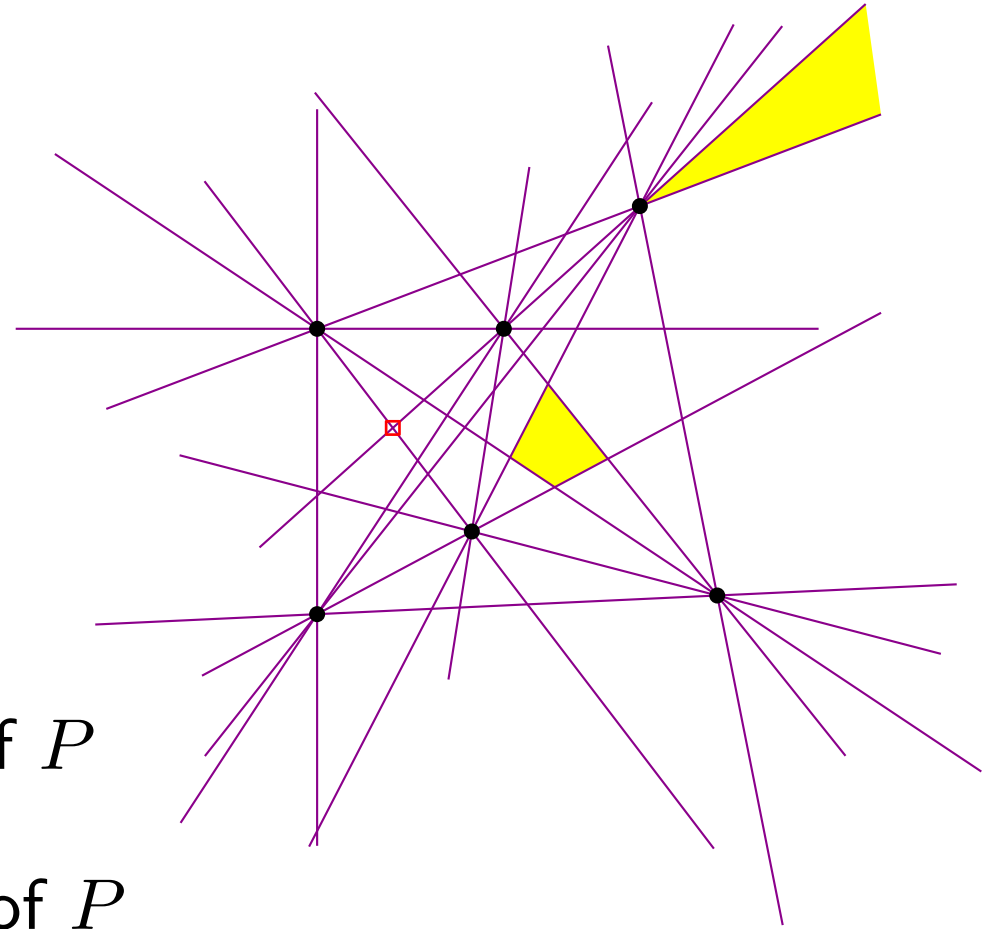


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- ★ the *convex hull* of P
- ★ the *Delaunay triangulation* of P
- ★ the *minimum spanning tree* of P
- ★ the *arrangement* of the lines spanned by P



Complexity analysis

Predict the size of a data structure.

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function of n (# of points), d (dimension)...

"Input points" considered over \mathbb{R}^d

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Convex hull: $\Theta\left(n^{\lfloor d/2 \rfloor}\right)$

Delaunay triangulation: $\Theta\left(n^{\lceil d/2 \rceil}\right)$

Minimum spanning tree: $n - 1$

Arrangement of induced hyperplanes: $\Theta\left(n^{d^2}\right)$

First limit: structure

Worst-case bounds often **pessimistic** in practical situations, when data is **structured**.

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Find **properties** that rule out standard lower bounds.

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Still no good model of "computer graphic scene" ...

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Example of 3D Delaunay triangulation:

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"Nice" sample of a "nice" surface

[GN 02], [GN03], [ABL 03], [DEG 08], [AAD 09]

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Size of DT \leftrightarrow "dimension" of the point set.

Second limit: precision

Input points given in **finite-precision** arithmetic.

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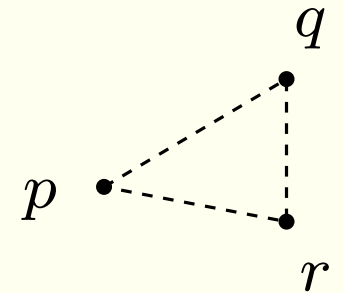
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$$f(p, q, r) = R \text{ and } f(p, r, q) = L.$$



There exists an order type s. t. all its realization have **exponential** bit complexity [PS 89].

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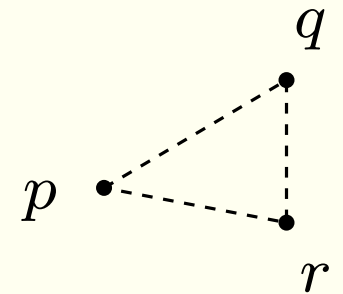
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Data is often **noisy**, lower-bounds are often **carefully designed**.

Problems

Geometric structures defined by finite-precision data?

Robustness of lower/upper bounds to noise?

Smoothed complexity analysis

General principles

Geometric probabilities

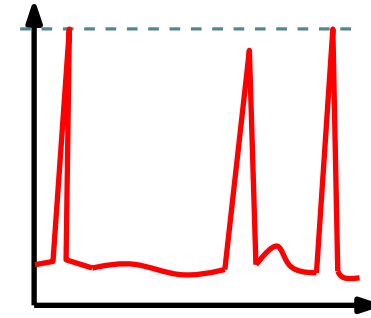
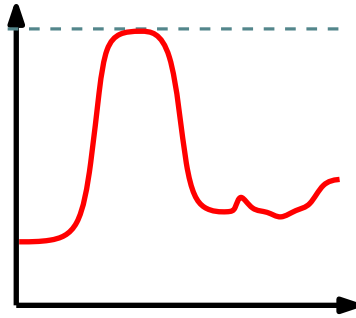
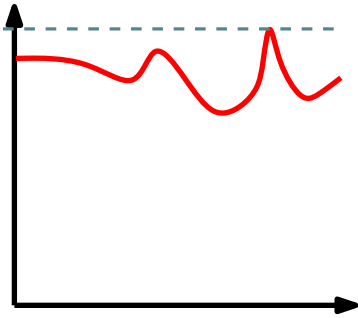
Shape matters

Smoothed complexity

"Worst-case complexity" = max. of the **complexity function**.

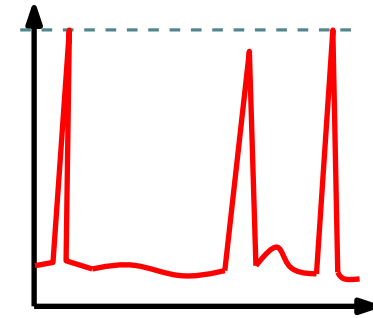
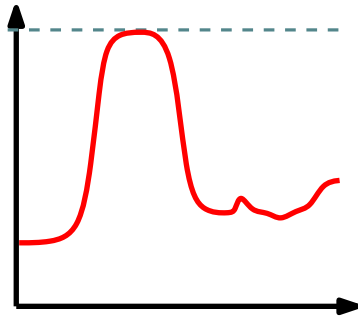
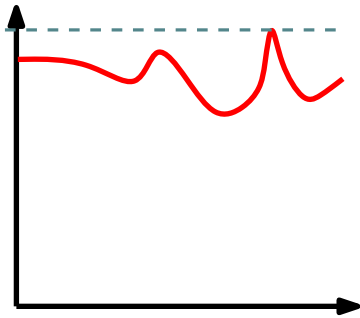
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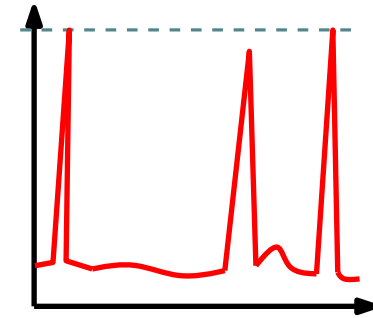
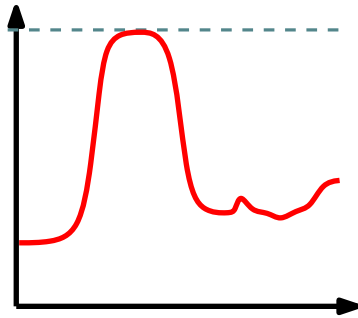
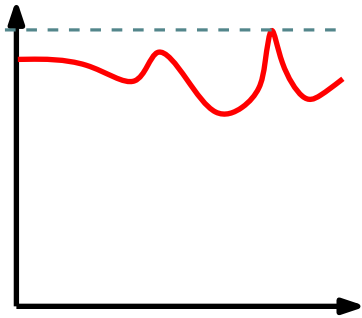


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\simeq Convolution with a distribution concentrated near the origin.

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Gödel prize in 2008

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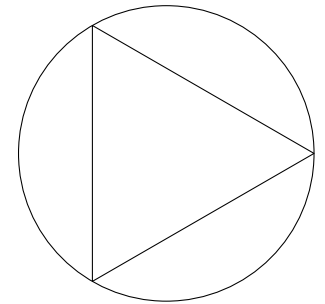
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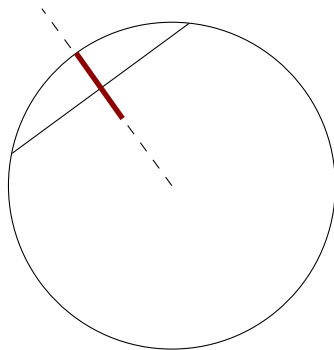
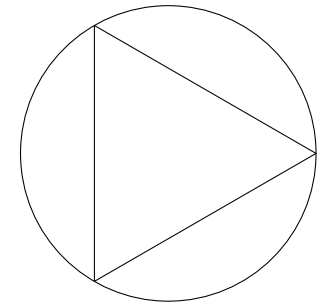


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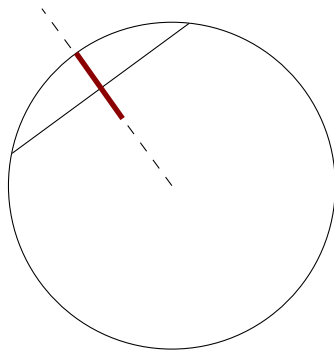
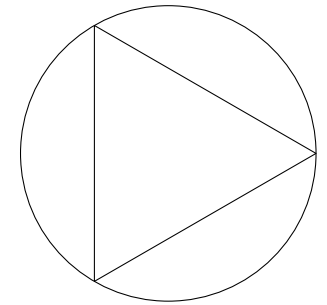
1/2

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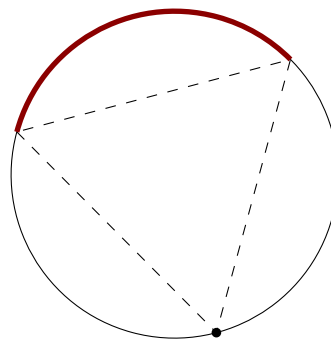
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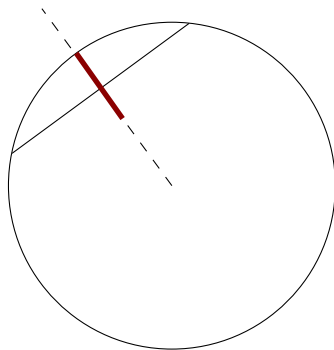
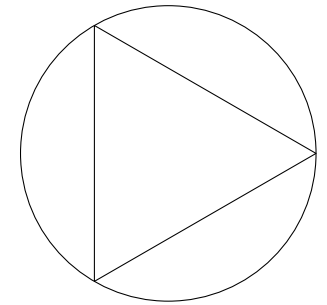
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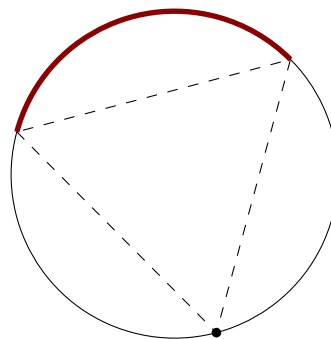
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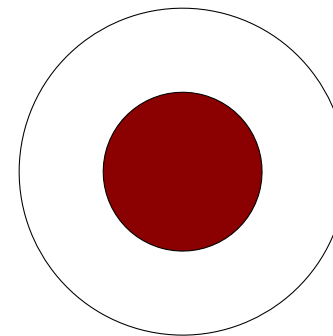
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Intuition: points chosen "close to corners" dominate many points.

Number of extreme points

The *shuffled convex hull* game

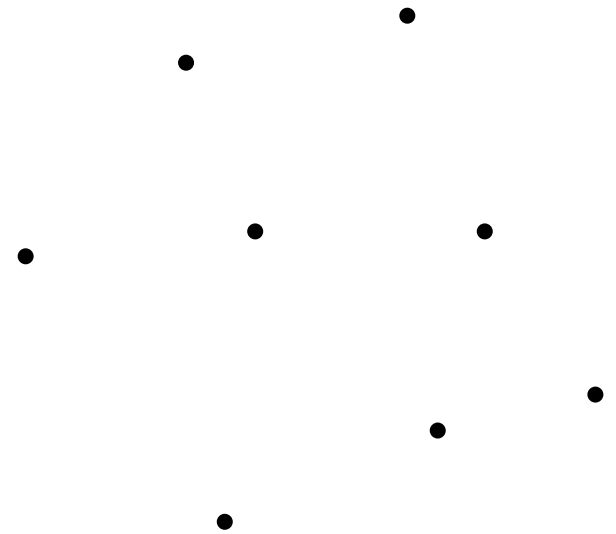
Our results

Comparison to "experimental" data

Shuffled convex hull game

Let X be a set of n points in some fixed domain D .

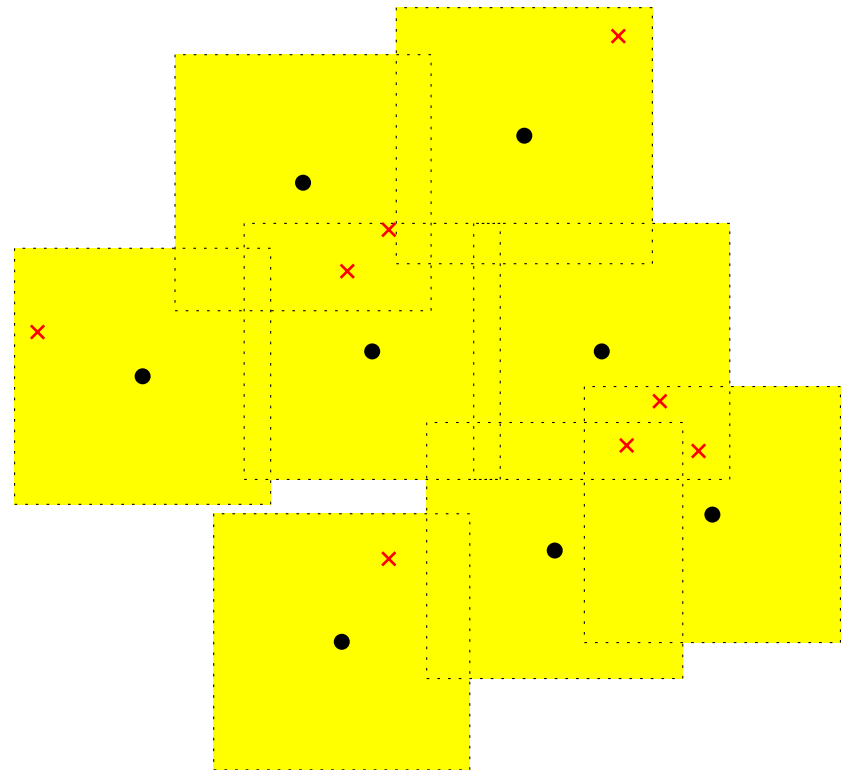
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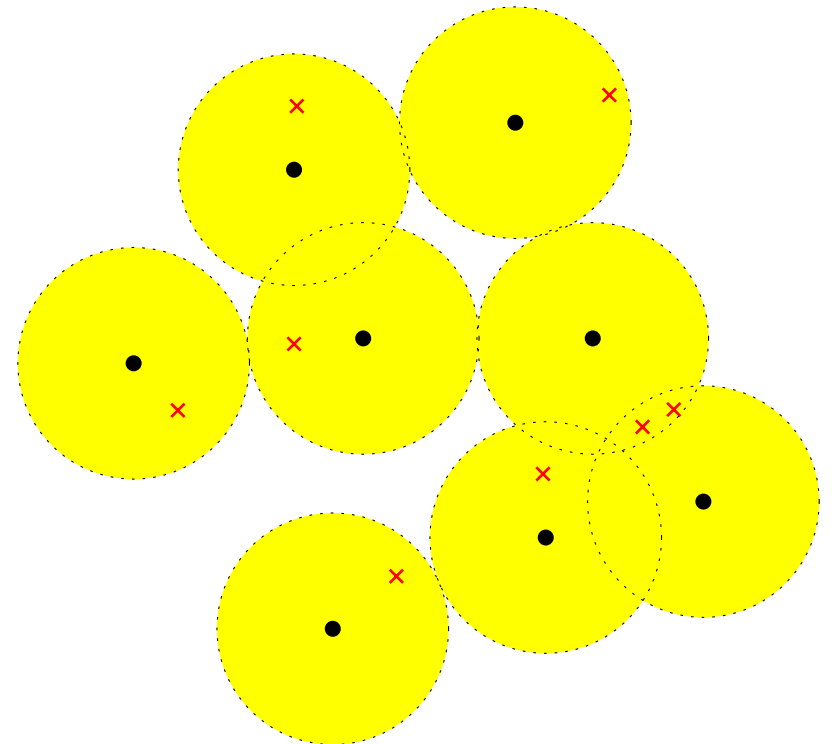
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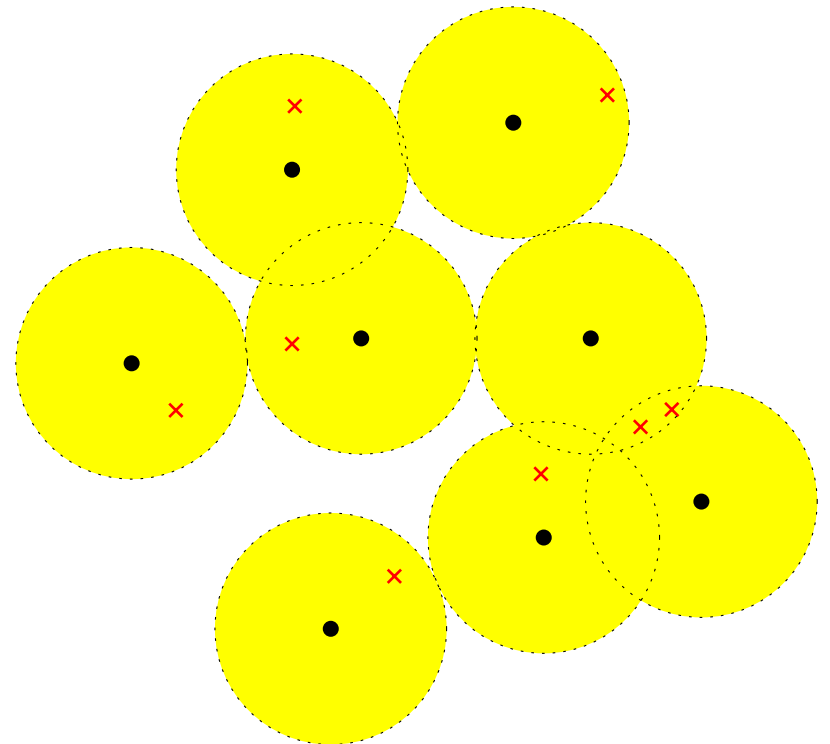
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Given ϵ and p , find X such that $E[\#CH(Y)]$ is max.

Different D , different answers?



Our results

X = regular n -gon inscribed in the unit circle.

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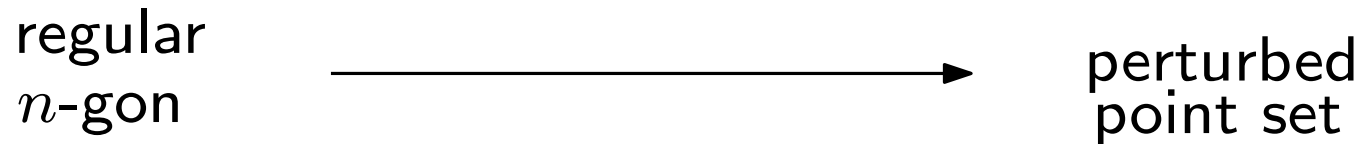
perturbation	$E[\#CH(Y)]$	range of δ
L^1, L^∞	$\tilde{\Theta}(n^{1/5}\delta^{-2/5})$	$\delta \in (\tilde{\Omega}(1/n^2), O(1))$
L^2	$\tilde{\Theta}(n^{1/4}\delta^{-3/8})$	

Comparison to exp. data

Uniform noise **simulated** by pseudo-random number generators.

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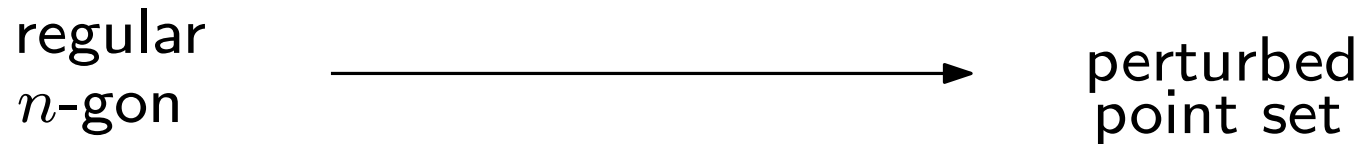
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2. random perturbation of the coordinates

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$$n = 10^i \text{ for } i = 3, \dots, 7$$

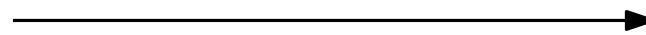
$$\delta = 10^j \text{ for } j = -7, \dots, 5$$

average over 1000 - 100 trials

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 n -gon



perturbed
point set

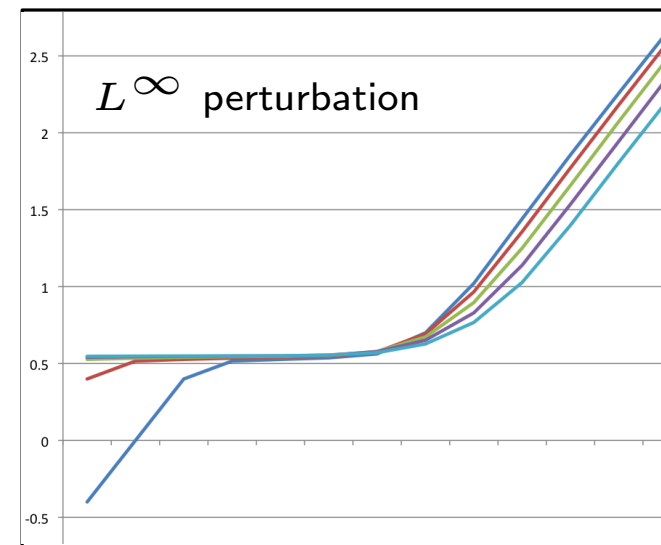
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Plot $\log_{10} \#CH(Y) - \log_{10}(n^{1/5} \delta^{-2/5})$



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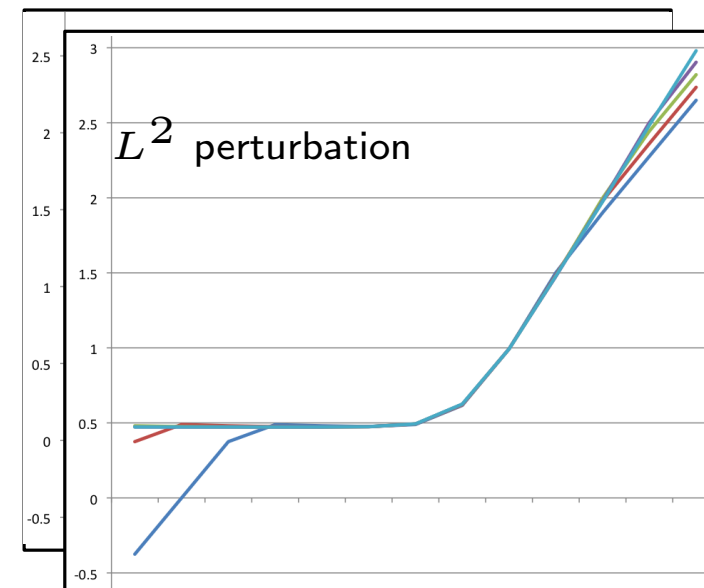
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Comparison to exp. data

Effect of **rounding** coordinates to a **coarse** grid.

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rounded
point set

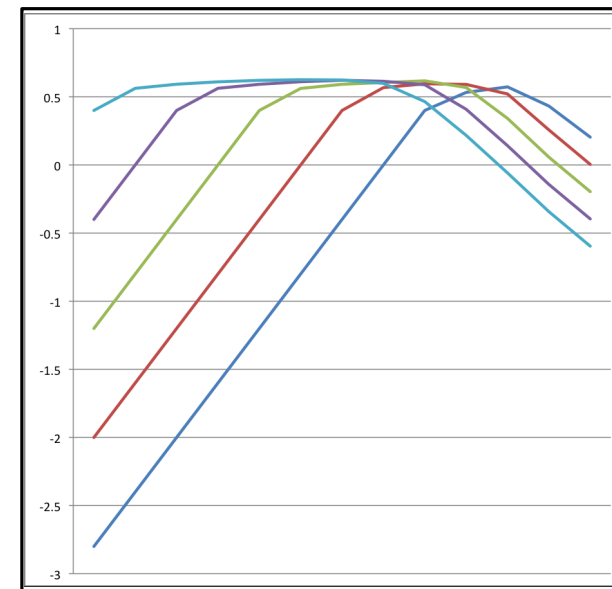
1. rounding to the *double* grid
2. rounding to the *float* grid.

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To summarize

Near-tight bounds for L^2 and L^∞ .

Predicts the behavior of regular rounding quite accurately.

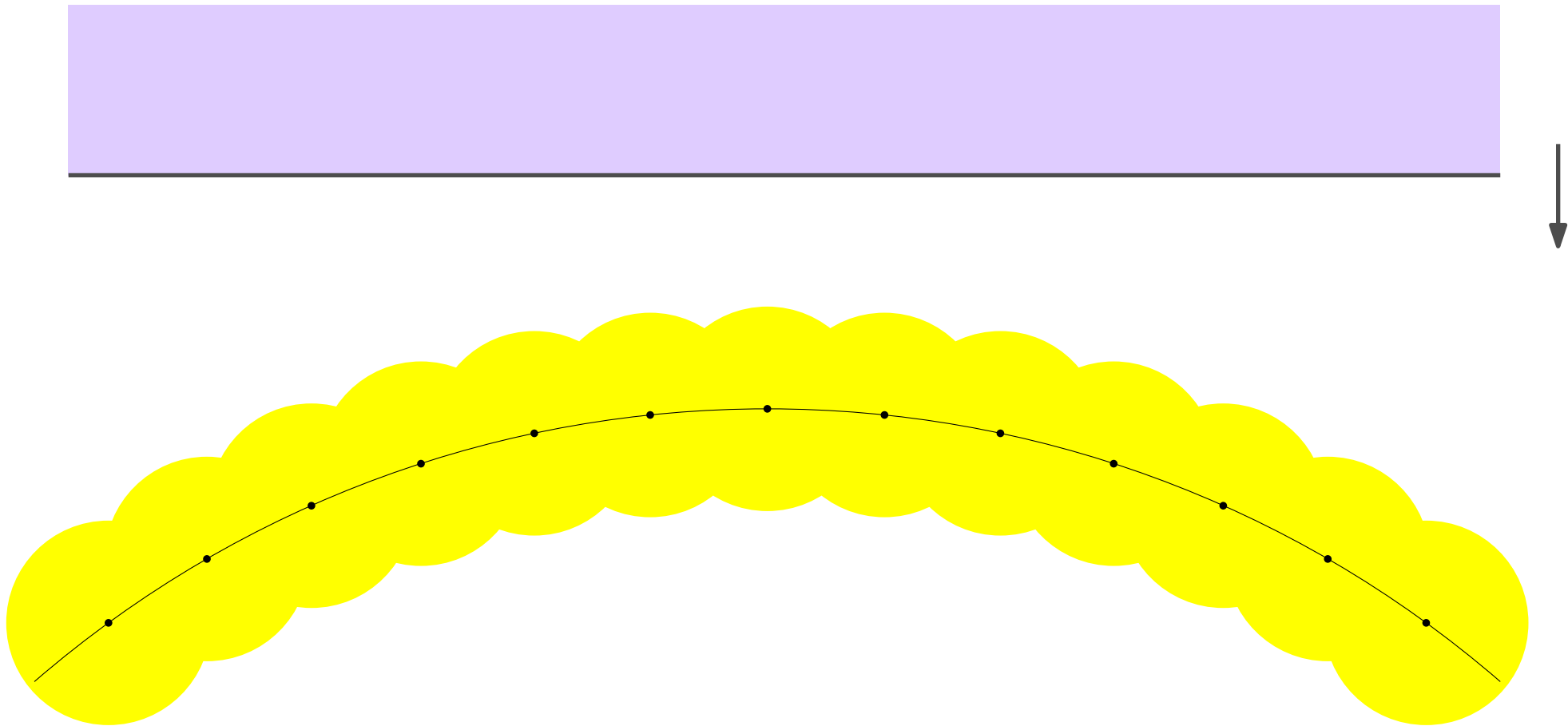
Generalizes to arbitrary dimension for L^2 perturbations.

A look under the hood

Witnesses and collectors

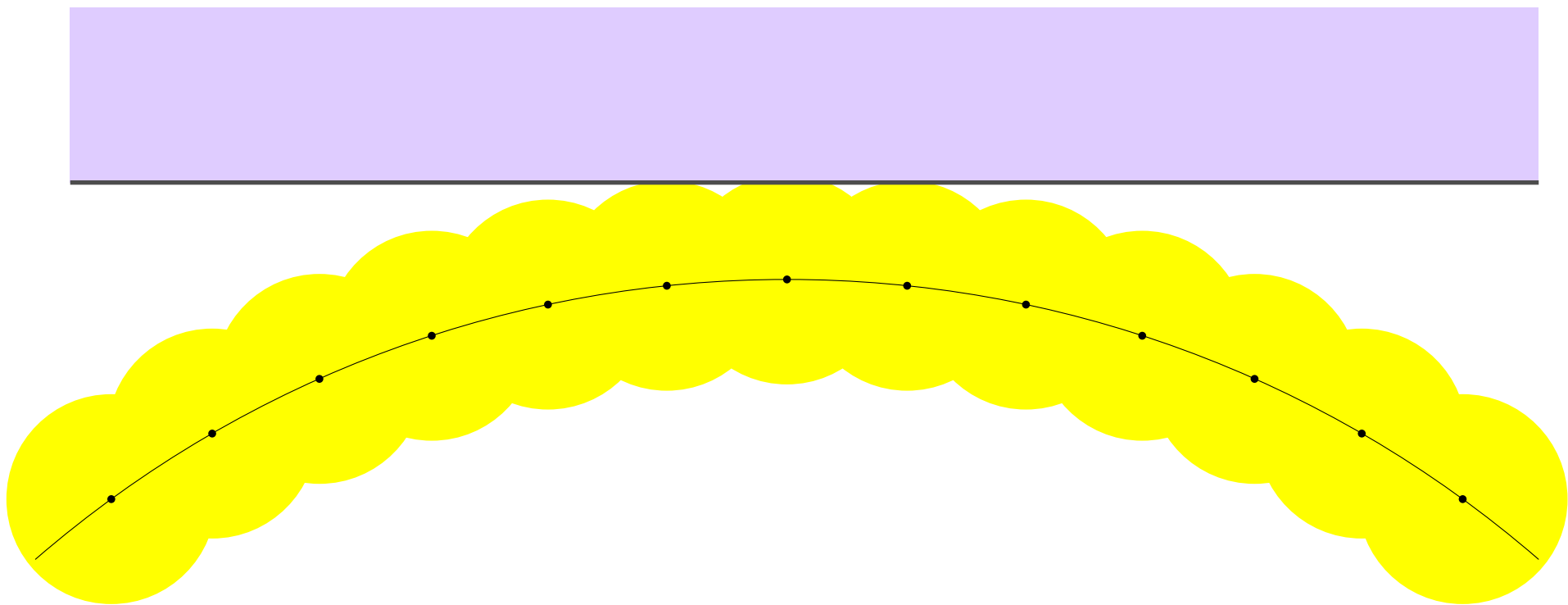
Shape matters (bis)

Principle



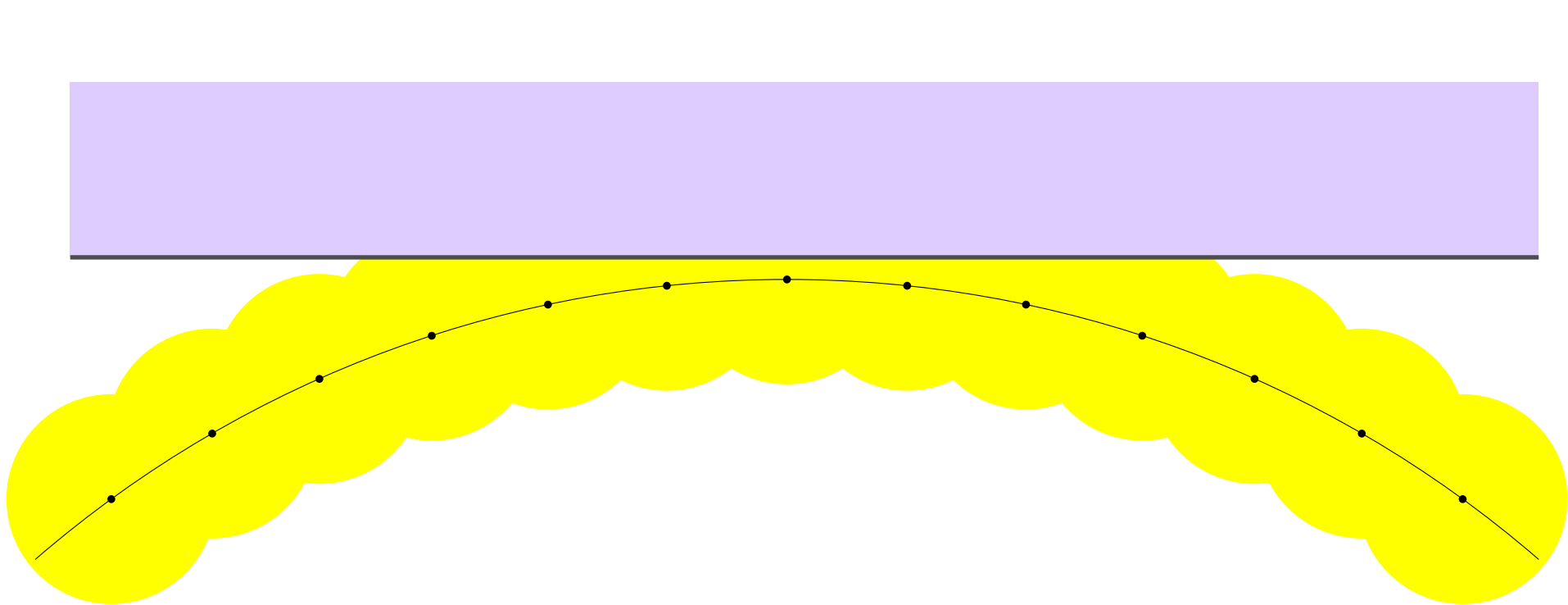
Push a halfplane and count the average # of points it contains.

Principle



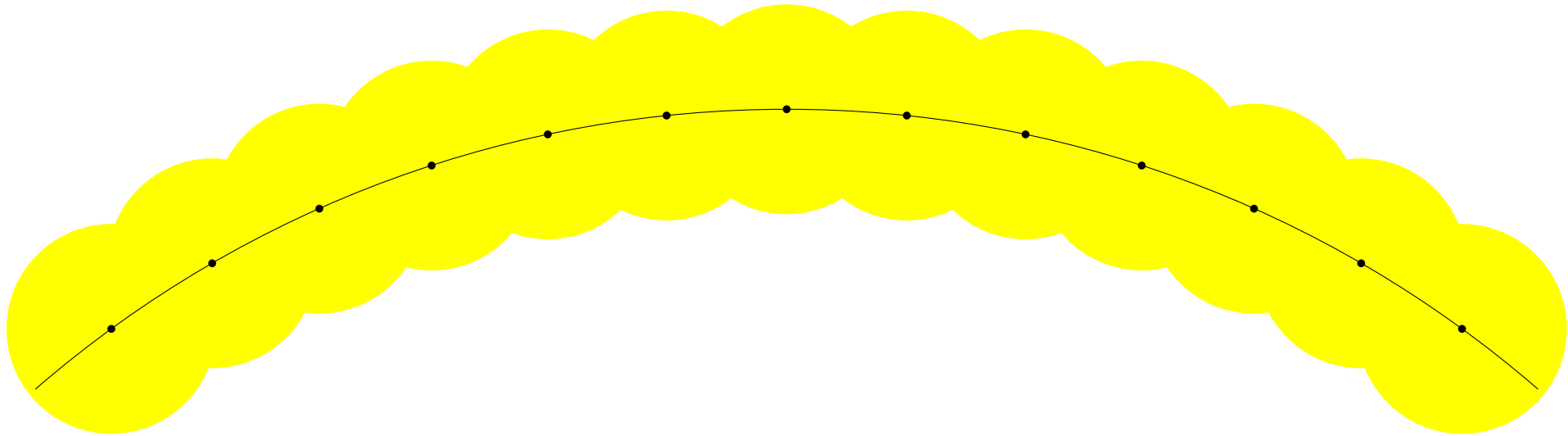
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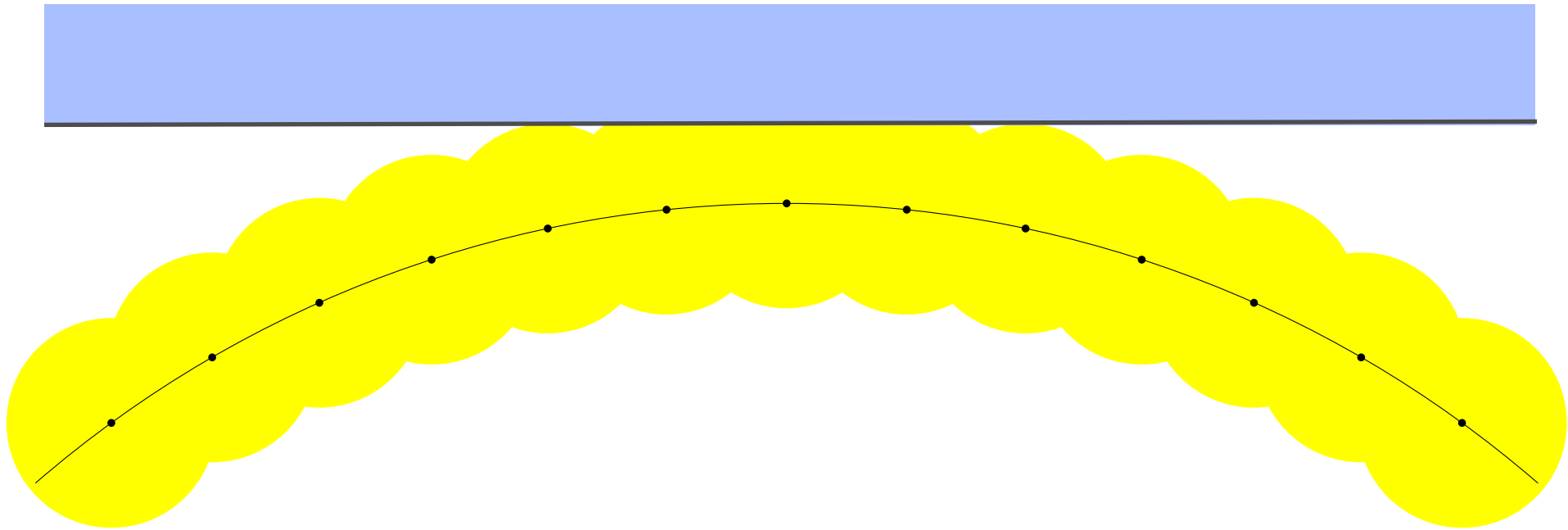


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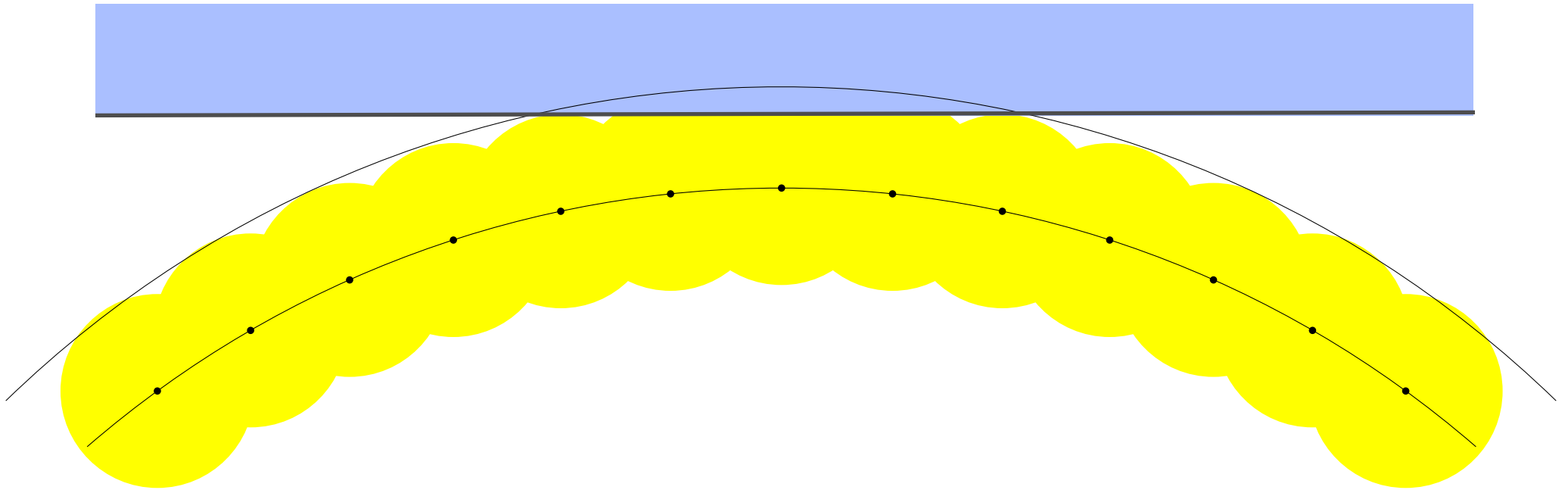
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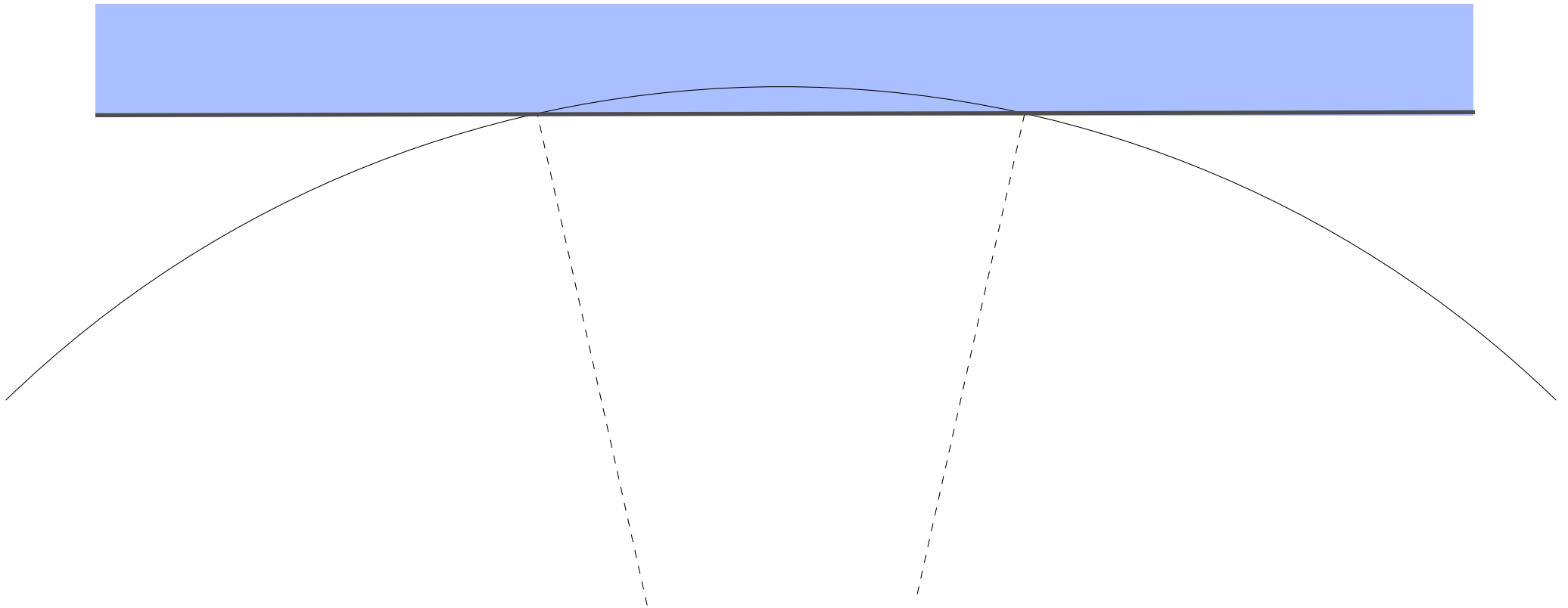
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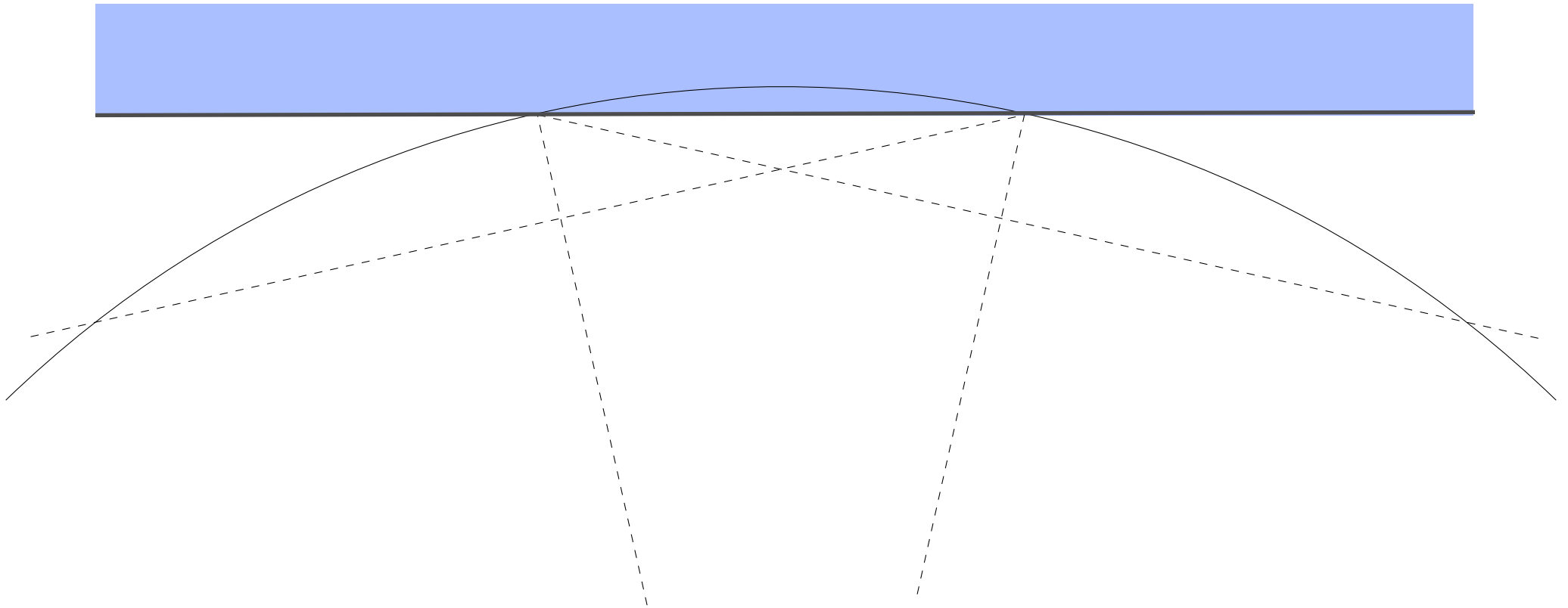
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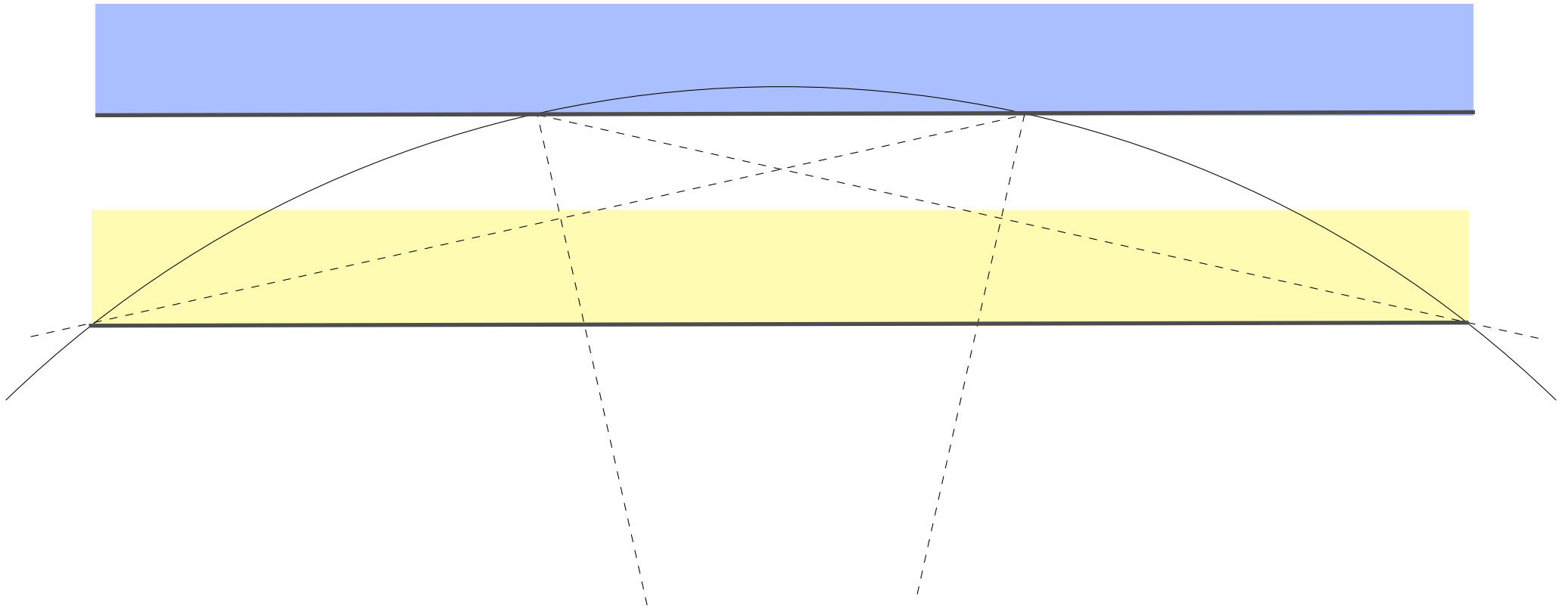
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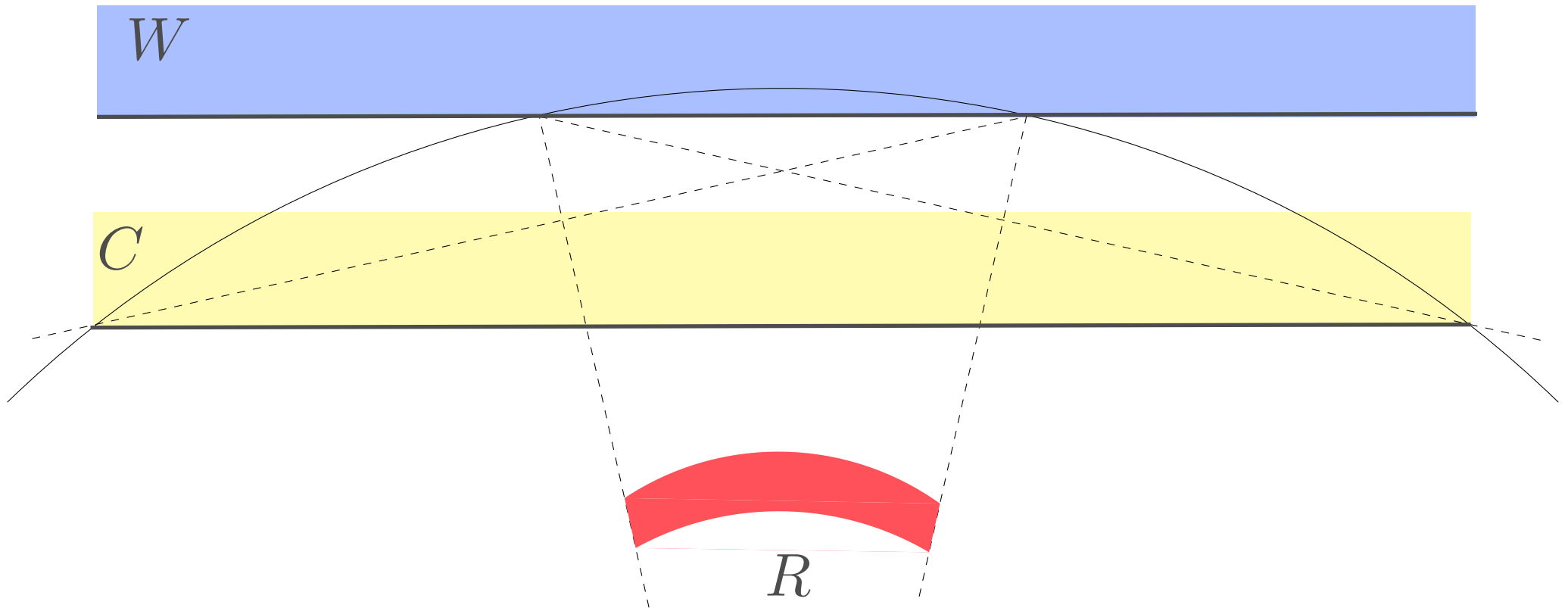
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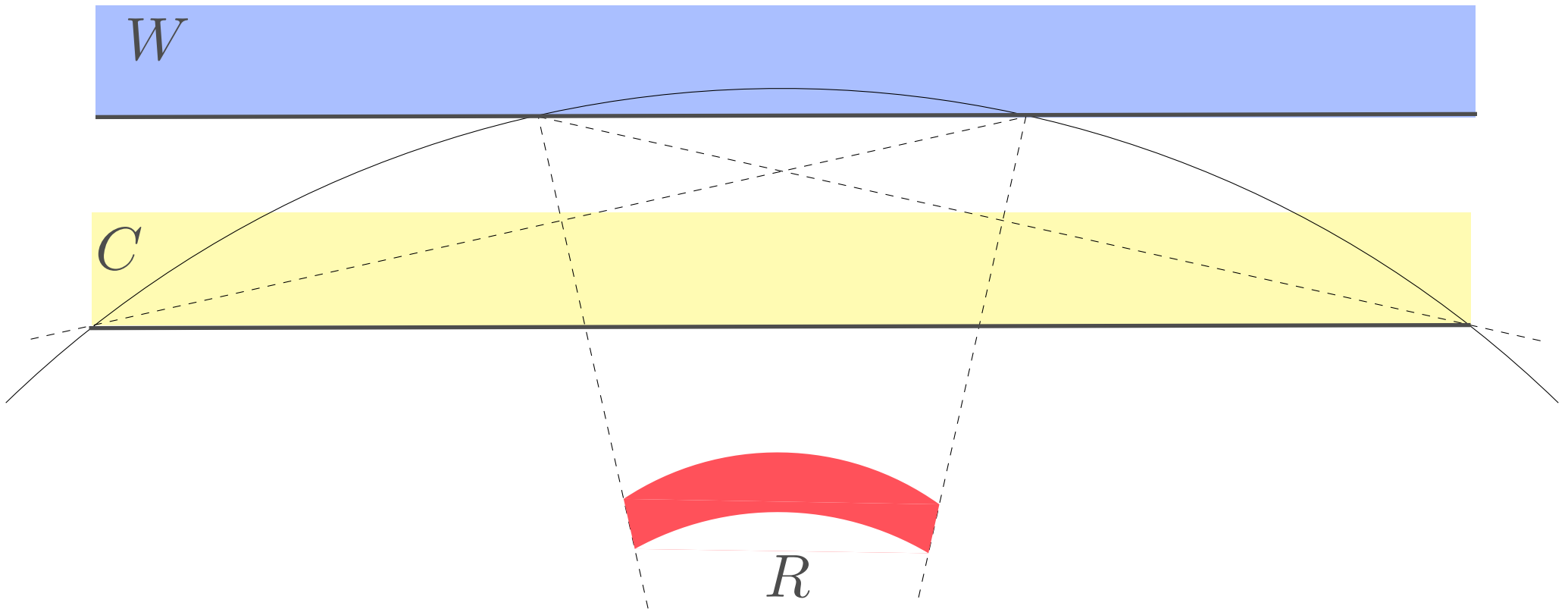
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Any point in W dominates any point **outside** C for any direction in R .

Witnesses & collectors

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... while having any perturbation disk meet **$O(1)$** W 's.

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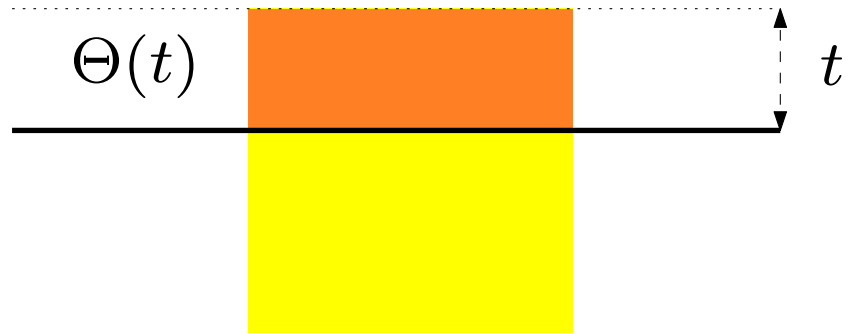
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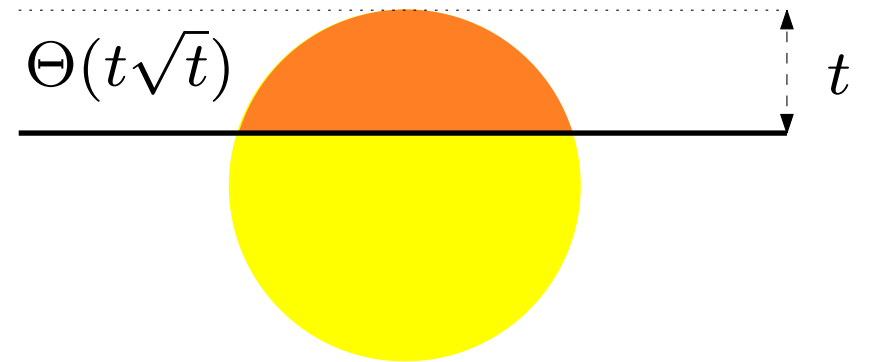
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$$\Rightarrow E[\#CH(Y)] = \Theta(\# \text{ pairs } (C, W))$$

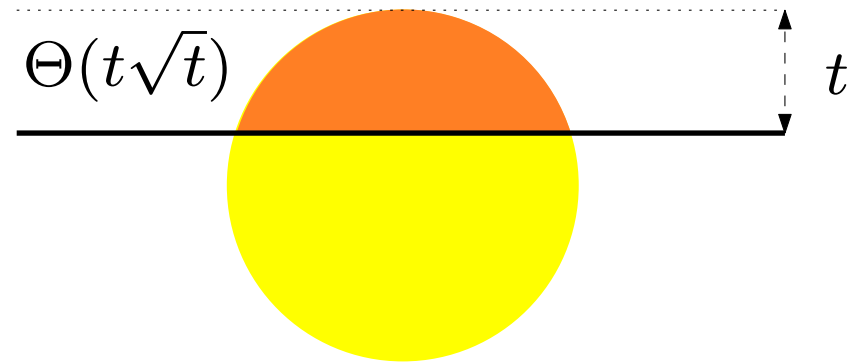
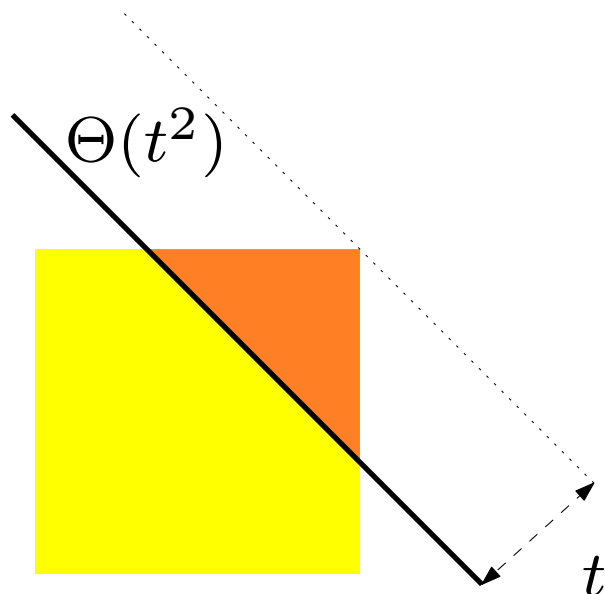
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